



LINEAR ALGEBRA

Homework 5 of April 03, 2014

Spring Semester 2014
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Deadline: April 10, 2014

Problem 1 (20%)

Bases and Rank

a) (10%) U comes from A by subtracting row 1 from row 3:

$$A = \begin{bmatrix} 1 & 3 & 2 \\ 0 & 1 & 1 \\ 1 & 3 & 2 \end{bmatrix} \text{ and } U = \begin{bmatrix} 1 & 3 & 2 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix}.$$

Find bases for the two column spaces, $C(A)$ and $C(U)$. Find bases for the two row spaces, $R(A)$ and $R(U)$. Find bases for the two nullspaces, $N(A)$ and $N(U)$.

b) (10%) For which numbers c and d do the below two matrices have exactly rank 2?

$$B = \begin{bmatrix} 1 & 2 & 5 & 0 & 5 \\ 0 & 0 & c & 2 & 2 \\ 0 & 0 & 0 & d & 2 \end{bmatrix} \text{ and } C = \begin{bmatrix} c & d \\ d & c \end{bmatrix}.$$

Solution

a) From eliminations, we have

$$\begin{aligned} E_{1,3}A &= \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -1 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 3 & 2 \\ 0 & 1 & 1 \\ 1 & 3 & 2 \end{bmatrix} = \begin{bmatrix} 1 & 3 & 2 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix} = U \\ \Rightarrow E_{1,2}U &= \begin{bmatrix} 1 & -3 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 3 & 2 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix} = R, \end{aligned}$$

where R is the row reduced echelon form of A. Therefore, based on Slides 3-52 and 3-53, we know $C(A) \neq C(U)$, $R(A) = R(U)$ and $N(A) = N(U)$, and the corresponding pivot columns of R determine the basis of $C(A)$ and $C(U)$. We then have the first and second columns of A are the basis for $C(A)$, the first and second columns of U are the basis for $C(U)$, and the first and second rows of A or U are bases for $R(A)$ and $R(U)$.

To find the nullspaces, consider

$$R = \begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} I_{2 \times 2} & F_{2 \times 1} \\ O_{1 \times 2} & O_{1 \times 1} \end{bmatrix}.$$

Then

$$N = \begin{bmatrix} -F_{2 \times 1} \\ I_{1 \times 1} \end{bmatrix} = \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}.$$

Hence, the basis for both $N(A)$ and $N(U)$ is $\begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}$.

- b) Since the rank is 2, there are only two pivots. Now if c is the second pivot, the third row must be an all-zero row, which is not possible; hence, $c = 0$. Subtracting the second row from the third row yields

$$B' = \begin{bmatrix} 1 & 2 & 5 & 0 & 5 \\ 0 & 0 & 0 & 2 & 2 \\ 0 & 0 & 0 & d-2 & 0 \end{bmatrix}.$$

This indicates $d = 2$.

On the other hand, C becomes a rank-1 matrix only when the second column is a multiple of the third column and they are both non-zero vectors, i.e.,

$$\begin{bmatrix} c \\ d \end{bmatrix} = k \begin{bmatrix} d \\ c \end{bmatrix} \quad \text{for some } k \in \mathbb{R},$$

and one of c and d is non-zero. The above is valid only when $k = \pm 1$, i.e., $c = \pm d \neq 0$. When $c = d = 0$, C is reduced to rank 0. Thus, any c and d that do not satisfy $c = \pm d$ will make C a rank-2 matrix.

Problem 2 (20%)

Finding a Basis

Find a basis for each of the following subspaces of \mathbb{R}^4 :

- a) (5%) All vectors whose components are equal.
- b) (5%) All vectors whose components add to zero (also explain why it is a vector space).
- c) (5%) All vectors that are perpendicular to $\begin{bmatrix} 1 \\ 1 \\ 0 \\ 0 \end{bmatrix}$ and $\begin{bmatrix} 1 \\ 0 \\ 1 \\ 1 \end{bmatrix}$ (also explain why this forms a vector space).
- d) (5%) The column space and the nullspace of $I_{4 \times 4}$.

Solution

Note that the bases for these vector spaces are not unique!

a) $\begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}$ for the vector space consisting of all vectors $\begin{bmatrix} c \\ c \\ c \\ c \end{bmatrix}$.

- b) The set of all vectors whose components add to zero can be written as the set of vectors \mathbf{x} satisfying

$$[1 \ 1 \ 1 \ 1]\mathbf{x} = 0.$$

It is a vector space because it is the nullspace of matrix $A = [1 \ 1 \ 1 \ 1]$. The basis can then be obtained from the special solutions:

$$N = \begin{bmatrix} -1 & -1 & -1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}.$$

c) Again, the set of vectors that are perpendicular to both $\begin{bmatrix} 1 \\ 1 \\ 0 \\ 0 \end{bmatrix}$ and $\begin{bmatrix} 1 \\ 0 \\ 1 \\ 1 \end{bmatrix}$ must satisfy

$$A\mathbf{x} = \begin{bmatrix} 1 & 1 & 0 & 0 \\ 1 & 0 & 1 & 1 \end{bmatrix} \mathbf{x} = \mathbf{0}.$$

So it is the nullspace of A. From the reduced row echelon form of A,

$$\begin{bmatrix} 1 & 1 & 0 & 0 \\ 1 & 0 & 1 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & 0 & 0 \\ 0 & -1 & 1 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 1 & 1 \\ 0 & -1 & 1 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 1 & 1 \\ 0 & 1 & -1 & -1 \end{bmatrix},$$

the basis of the nullspace of A can be obtained from the two columns of:

$$N = \begin{bmatrix} -1 & -1 \\ 1 & 1 \\ 1 & 0 \\ 0 & 1 \end{bmatrix}.$$

d) Since the rank of identity matrix I is 4, the column space C(I) is equal to \mathbb{R}^4 and the nullspace N(I) is given by $\{\mathbf{0}\}$. For the former, we choose the standard basis $\begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}$, $\begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}$, $\begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}$ and $\begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}$. For the latter, there is no basis; so the set of basis is an empty set.

Problem 3 (20%)

Basis of a Vector Space of Matrices

Find a basis and the dimension for each of the spaces formed by the following matrices. Also explain why they are vector spaces.

- a) (5%) All diagonal 3×3 matrices.
- b) (5%) All symmetric 3×3 matrices ($A^T = A$).
- c) (5%) All 3×3 skew-symmetric matrices ($A^T = -A$).
- d) (5%) All 2×3 matrices whose columns add to zero.

Solution

a) It is a vector space because any 3×3 diagonal matrix can be expressed as

$$\begin{bmatrix} d_1 & 0 & 0 \\ 0 & d_2 & 0 \\ 0 & 0 & d_3 \end{bmatrix} = d_1 \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} + d_2 \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} + d_3 \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}.$$

The three matrices

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

are linearly independent because one cannot be represented as a linear combination of the other two. They then form the basis and the dimension of the vector space is 3.

b) Again, it is a vector space since any symmetric matrix can be decomposed to

$$\begin{bmatrix} d_1 & a & b \\ a & d_2 & c \\ b & c & d_3 \end{bmatrix} = d_1 \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} + d_2 \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} + d_3 \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \\ + a \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} + b \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix} + c \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}.$$

The basis are the six matrices listed on the right-hand-side above, and the dimension is 6.

c) The reason for the space of all skew-symmetric matrices is a vector space is the same as ???. Note that there are no diagonal entries for skew-symmetric matrices; so the basis should be

$$\begin{bmatrix} 0 & 1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ -1 & 0 & 0 \end{bmatrix}, \text{ and } \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & -1 & 0 \end{bmatrix}.$$

Hence, the dimension is 3.

d) The dimension of this vector space is 3, and the three basis vectors chosen can be

$$\begin{bmatrix} 1 & 0 & 0 \\ -1 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 & 0 \\ 0 & -1 & 0 \end{bmatrix}, \text{ and } \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & -1 \end{bmatrix}.$$

Problem 4 (20%)

Extension to Matrix Space

Determine all the matrices whose nullspace is spanned by $\begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix}$.

Hint: Read Slides 3-57 and 3-58.

Solution

The problem is the same as finding all the matrices whose row space is spanned by the two (linearly independent) vectors perpendicular to $\begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} -\mathbb{F}_{2 \times 1} \\ \mathbb{I}_{1 \times 1} \end{bmatrix}$. So one choice of the bases of the row space is given by

$$[\mathbb{I}_{2 \times 2} \quad \mathbb{F}_{2 \times 1}] = \begin{bmatrix} 1 & 0 & -2 \\ 0 & 1 & -1 \end{bmatrix}.$$

Therefore, all rank-2 $m \times 3$ matrices whose rows are linear combinations of the above two row vectors give the solution (hence, $m \geq 2$), i.e.,

$$A_{m \times 3} = C_{m \times 2} \begin{bmatrix} 1 & 0 & -2 \\ 0 & 1 & -1 \end{bmatrix}_{2 \times 3} = \begin{bmatrix} c_{1,1} & c_{1,2} \\ c_{2,1} & c_{2,2} \\ \vdots & \vdots \\ c_{m,1} & c_{m,2} \end{bmatrix} \begin{bmatrix} 1 & 0 & -2 \\ 0 & 1 & -1 \end{bmatrix},$$

where at least two rows of C are not multiple of each other.

Problem 5 (20%)

Determination of the Left Nullspace

- a) (10%) Check whether all solutions to matrix equation $Ax = \mathbf{0}$ are perpendicular to the rows of $R = \text{rref}(A)$, where

$$A = \tilde{E}R = \begin{bmatrix} 4 & 0 & 0 \\ 8 & 1 & 0 \\ 12 & 4 & 1 \end{bmatrix} \begin{bmatrix} 1 & \frac{1}{2} & 0 & \frac{1}{4} \\ 0 & 0 & 1 & 3 \\ 0 & 0 & 0 & 0 \end{bmatrix}.$$

- b) (10%) Find a basis of the left nullspace of A . Based on Slides 3-60 and 3-61, explain why one choice of bases of the left nullspace of A can be the last row of $E \triangleq \tilde{E}^{-1}$.

Solution

- a) All the solutions of matrix equation $Ax = \mathbf{0}$ form the nullspace of A ; so they are all the linear combinations of the column vectors of:

$$N = \begin{bmatrix} -\frac{1}{2} & -\frac{1}{4} \\ 1 & 0 \\ 0 & -3 \\ 0 & 1 \end{bmatrix}.$$

Since both $\begin{bmatrix} -\frac{1}{2} \\ 1 \\ 0 \\ 0 \end{bmatrix}$ and $\begin{bmatrix} -\frac{1}{4} \\ 0 \\ -3 \\ 1 \end{bmatrix}$ are perpendicular to the rows of R , so are their linear combinations.

- b) Since $A = \tilde{E}R$, we have

$$\begin{aligned} \tilde{E}^{-1}A = EA &= \begin{bmatrix} \frac{1}{4} & 0 & 0 \\ -2 & 1 & 0 \\ 5 & -4 & 1 \end{bmatrix} A = \begin{bmatrix} E_{2 \times 3} \\ \mathbf{e}_3^T \end{bmatrix} A_{3 \times 4} = \begin{bmatrix} E_{2 \times 3} A_{3 \times 4} \\ \mathbf{e}_3^T A_{3 \times 4} \end{bmatrix} = R = \begin{bmatrix} 1 & \frac{1}{2} & 0 & \frac{1}{4} \\ 0 & 0 & 1 & 3 \\ 0 & 0 & 0 & 0 \end{bmatrix} \\ \implies \mathbf{e}_3^T A &= \mathbf{0} \implies A^T \mathbf{e}_3 = \mathbf{0}. \end{aligned}$$

Therefore, $\mathbf{e}_3 = \begin{bmatrix} 5 \\ -4 \\ 1 \end{bmatrix}$ that is the last row of E can be a basis of the left nullspace of A .